

**Numerical Methods of  
Electromagnetic Field Theory II (NFT II)  
Numerische Methoden der  
Elektromagnetischen Feldtheorie II (NFT II) /**

**3rd Lecture / 3. Vorlesung**

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**2-D Versions of EFIE and MFIE: TM and TE Case /  
2D-Versionen von EFIE und MFIE: TM- und TE-Fall**

2-D Case /  
2D-Fall

Position Vector / Ortsvektor

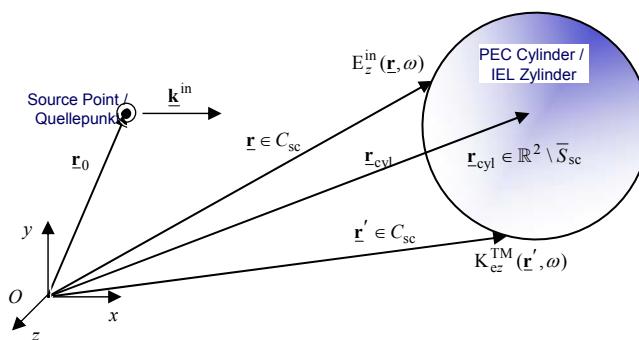
$$\underline{R} = x\underline{e}_x + y\underline{e}_y + z\underline{e}_z \Big|_{z=0} = \underbrace{x\underline{e}_x + y\underline{e}_y}_{=r\underline{e}_r(\varphi)} + \underbrace{z\underline{e}_z}_{=0} = \underbrace{r\underline{e}_r(\varphi)}_{=\underline{r}} = \underline{r}$$

Field Quantities / Feldgrößen

$$\{\underline{E}(\underline{R}, \omega), \underline{H}(\underline{R}, \omega), \underline{K}_e(\underline{R}, \omega), \underline{K}_m(\underline{R}, \omega)\} \Big|_{z=0} \rightarrow \{\underline{E}(\underline{r}, \omega), \underline{H}(\underline{r}, \omega), \underline{K}_e(\underline{r}, \omega), \underline{K}_m(\underline{r}, \omega)\}$$

$$\frac{\partial}{\partial z} \equiv 0$$

All Field Quantities and the Geometry are Independent of z /  
Alle Feldgrößen und die Geometrie sind von z unabhängig



## 2-D Versions of EFIE and MFIE: TM and TE Case / 2D-Versionen von EFIE und MFIE: TM- und TE-Fall

Boundary Condition / Randbedingung

$$\underline{n}_{sc} \times \underline{E}(\underline{r}, \omega) = \underline{0}$$

$$\rightarrow \underline{K}_m(\underline{r}, \omega) = \underline{0}$$

$$\rightarrow \underline{K}_e(\underline{r}, \omega) \neq \underline{0}$$

$$\underline{n}_{sc} \times \underline{E}(\underline{r}, \omega) = \underline{n}_{sc} \times \underline{E}^{in}(\underline{r}, \omega) + \underline{n}_{sc} \times \underline{E}^{sc}(\underline{r}, \omega)$$

$$= \underline{0}$$

$$\underline{n}_{sc} \times \underline{E}^{sc}(\underline{r}, \omega) = -\underline{n}_{sc} \times \underline{E}^{in}(\underline{r}, \omega)$$

$$\underline{E}_t^{sc}(\underline{r}, \omega) = -\underline{E}_t^{in}(\underline{r}, \omega)$$

This means that the tangential component of the incident and scattered wavefield are pointing in the opposite direction at the scatterer surface /  
Dies bedeutet, dass die Tangentialkomponente des einfallenden und gestreuten Wellenfeldes auf der Streueroberfläche in die entgegen gesetzte Richtung zeigen.

For the Derivation of the 2-D PEC TM EFIE we start from the 3-D Franz-Larmor version of EFIE for the Scattered Electric Field Strength for /  
Zur Ableitung der 2D-PEC-TM-EFIE starten wir mit der 3D-Franz-Larmor-Version von EFIE für die gestreute elektrische Feldstärke für

$$\underline{R} \in \mathbb{R}^3 \setminus V_{sc}$$

Franz-Larmor version / Franz-Larmor-Version:

$$-\frac{1}{j\omega\epsilon_0} \underline{n}_{sc} \times \nabla \times \nabla \times \iint_{\underline{R}' \in S_{sc} = \partial V_{sc}} \underline{K}_e(\underline{R}', \omega) G(\underline{R} - \underline{R}', \omega) d^2 \underline{R}' = -\underline{n}_{sc} \times \underline{E}^{in}(\underline{R}, \omega)$$

## 2-D Versions of EFIE: TM Case / 2D-Versionen von EFIE: TM-Fall

Scattered Electric Field Strength /  
Gestreute elektrische Feldstärke

$$\underline{n}_{sc} \times \left[ -\frac{1}{j\omega\epsilon_0} \nabla \times \nabla \times \iint_{\underline{R}' \in S_{sc} = \partial V_{sc}} \underline{K}_e(\underline{R}', \omega) G(\underline{R} - \underline{R}', \omega) d^2 \underline{R}' \right] = -\underline{n}_{sc} \times \underline{E}^{in}(\underline{R}, \omega)$$

$$= \underline{E}^{sc}(\underline{R}, \omega)$$

$$\underline{E}^{sc}(\underline{R}, \omega) = -\frac{1}{j\omega\epsilon_0} \nabla \times \nabla \times \iint_{\underline{R}' \in S_{sc} = \partial V_{sc}} \underline{K}_e(\underline{R}', \omega) G(\underline{R} - \underline{R}', \omega) d^2 \underline{R}'$$

In the 2-D TM is only the  $E_z$  Component Unequal of Zero. That's Because we project the Electric Field Strength Onto the Unit Vector in  $z$  Direction /  
Im 2D-TM-Fall ist nur die  $E_z$ -Komponente ungleich von Null. Deshalb projizieren wir den elektrischen Feldstärkevektor auf den Einheitsvektor in  $z$ -Richtung

We take only the  $z$  Component of the above Integral Equation for the observation point outside the scattering volume /  
Wir nehmen nur die  $z$ -Komponente der oberen Integralgleichung für einen Beobachtungspunkt außerhalb des Streuvolumens

$$\underline{e}_z \cdot \underline{E}^{sc}(\underline{R}, \omega) = -\frac{1}{j\omega\epsilon_0} \underline{e}_z \cdot \nabla \times \nabla \times \iint_{\underline{R}' \in S_{sc} = \partial V_{sc}} \underline{K}_e(\underline{R}', \omega) G(\underline{R} - \underline{R}', \omega) d^2 \underline{R}'$$

## 2-D Versions of EFIE: TM Case / 2D-Versionen von EFIE: TM-Fall

Now we Apply the double curl operator and specialize the result for the 2-D TM case at the plane  $z=0$ . / Nun wenden wir den doppelten Rotationsoperator an und spezialisieren das Ergebnis für die Ebene  $z=0$ .

$$\underline{\epsilon}_z \cdot \nabla \times \nabla \times \iint_{\underline{\mathbf{R}}' \in S_{sc} = \partial V_{sc}} \underline{\mathbf{K}}_e(\underline{\mathbf{R}}', \omega) G(\underline{\mathbf{R}} - \underline{\mathbf{R}}', \omega) d^2 \underline{\mathbf{R}}' = \underline{\epsilon}_z \cdot \iint_{\underline{\mathbf{R}}' \in S_{sc} = \partial V_{sc}} \nabla \times \nabla \times [\underline{\mathbf{K}}_e(\underline{\mathbf{R}}', \omega) G(\underline{\mathbf{R}} - \underline{\mathbf{R}}', \omega)] d^2 \underline{\mathbf{R}}'$$

We compute for the double curl operator /  
Wir berechnen für den doppelten Rotationsoperator

$$\begin{aligned} \nabla \times \nabla \times [\underline{\mathbf{K}}_e(\underline{\mathbf{R}}', \omega) G(\underline{\mathbf{R}} - \underline{\mathbf{R}}', \omega)] &= \nabla \nabla \cdot [\underline{\mathbf{K}}_e(\underline{\mathbf{R}}', \omega) G(\underline{\mathbf{R}} - \underline{\mathbf{R}}', \omega)] - \nabla \cdot \nabla [\underline{\mathbf{K}}_e(\underline{\mathbf{R}}', \omega) G(\underline{\mathbf{R}} - \underline{\mathbf{R}}', \omega)] \\ &= \underline{\mathbf{K}}_e(\underline{\mathbf{R}}', \omega) \cdot \nabla \nabla G(\underline{\mathbf{R}} - \underline{\mathbf{R}}', \omega) - \underline{\mathbf{K}}_e(\underline{\mathbf{R}}', \omega) \nabla \cdot \nabla G(\underline{\mathbf{R}} - \underline{\mathbf{R}}', \omega) \end{aligned}$$

For all points outside the Scattering Volume we find /  
Für alle Punkte außerhalb des Streuvolumens finden wir

$$\begin{aligned} \nabla \nabla G(\underline{\mathbf{R}} - \underline{\mathbf{R}}', \omega) &= k_0^2 \left\{ -\widehat{(\underline{\mathbf{R}} - \underline{\mathbf{R}}')} \widehat{(\underline{\mathbf{R}} - \underline{\mathbf{R}}')} + \frac{j}{k_0 |\underline{\mathbf{R}} - \underline{\mathbf{R}}'|} \left[ \underline{\mathbf{I}} - 3 \widehat{(\underline{\mathbf{R}} - \underline{\mathbf{R}}')} \widehat{(\underline{\mathbf{R}} - \underline{\mathbf{R}}')} \right] \right. \\ &\quad \left. - \frac{1}{k_0^2 |\underline{\mathbf{R}} - \underline{\mathbf{R}}'|} \left[ \underline{\mathbf{I}} - 3 \widehat{(\underline{\mathbf{R}} - \underline{\mathbf{R}}')} \widehat{(\underline{\mathbf{R}} - \underline{\mathbf{R}}')} \right] \right\} G(\underline{\mathbf{R}} - \underline{\mathbf{R}}', \omega) \end{aligned}$$

$$\nabla \cdot \nabla G(\underline{\mathbf{R}} - \underline{\mathbf{R}}', \omega) = -k_0^2 G(\underline{\mathbf{R}} - \underline{\mathbf{R}}', \omega)$$

## 2-D Versions of EFIE: TM Case / 2D-Versionen von EFIE: TM-Fall

$$\nabla \times \nabla \times [\underline{\mathbf{K}}_e(\underline{\mathbf{R}}', \omega) G(\underline{\mathbf{R}} - \underline{\mathbf{R}}', \omega)] = \underline{\mathbf{K}}_e(\underline{\mathbf{R}}', \omega) \cdot \nabla \nabla G(\underline{\mathbf{R}} - \underline{\mathbf{R}}', \omega) - \underline{\mathbf{K}}_e(\underline{\mathbf{R}}', \omega) \nabla \cdot \nabla G(\underline{\mathbf{R}} - \underline{\mathbf{R}}', \omega)$$

We now consider the  $z$  independent case and an electric surface current density of the form /  
Wir betrachten nun den von  $z$  unabhängigen Fall und eine elektrische Flächenstromdichte von der Form

$$\begin{aligned} \underline{\mathbf{K}}_e(\underline{\mathbf{R}}', \omega) &= \underline{\mathbf{K}}_e^{TM}(\underline{\mathbf{R}}', \omega) \\ &= K_{ez}^{TM}(\underline{\mathbf{R}}', \omega) \underline{\epsilon}_z \end{aligned}$$

and find /  
und finden

$$\begin{aligned} \underline{\epsilon}_z \cdot \left[ \underline{\mathbf{K}}_e(\underline{\mathbf{R}}', \omega) \cdot \nabla \nabla G(\underline{\mathbf{R}} - \underline{\mathbf{R}}', \omega) \right]_{z=0} &= \underline{\epsilon}_z \left[ K_{ez}^{TM}(\underline{\mathbf{R}}', \omega) \underline{\epsilon}_z \cdot \nabla \nabla G(\underline{\mathbf{R}} - \underline{\mathbf{R}}', \omega) \right]_{z=0} \\ &= K_{ez}^{TM}(\underline{\mathbf{R}}', \omega) \underbrace{\underline{\epsilon}_z \underline{\epsilon}_z}_{\hat{\partial}^2} \cdot \nabla \nabla G(\underline{\mathbf{R}} - \underline{\mathbf{R}}', \omega) \Big|_{z=0} \\ &= \frac{\hat{\partial}^2}{\partial z^2} \\ &= K_{ez}^{TM}(\underline{\mathbf{R}}', \omega) \frac{\partial^2}{\partial z^2} G(\underline{\mathbf{R}} - \underline{\mathbf{R}}', \omega) \Big|_{z=0} \\ &= 0 \end{aligned}$$

## 2-D Versions of EFIE: TM Case / 2D-Versionen von EFIE: TM-Fall

$$\begin{aligned}
& \underline{\epsilon}_z \cdot \left[ \underline{K}_{ez}(\underline{\mathbf{R}}', \omega) \nabla \cdot \nabla G(\underline{\mathbf{R}} - \underline{\mathbf{R}}', \omega) \right]_{z=0} = \underline{\epsilon}_z \cdot \left[ K_{ez}^{\text{TM}}(\underline{\mathbf{R}}', \omega) \underline{\epsilon}_z \nabla \cdot \nabla G(\underline{\mathbf{R}} - \underline{\mathbf{R}}', \omega) \right]_{z=0} \\
& = \left[ K_{ez}^{\text{TM}}(\underline{\mathbf{R}}', \omega) \underline{\epsilon}_z \cdot \underline{\epsilon}_z \nabla \cdot \nabla G(\underline{\mathbf{R}} - \underline{\mathbf{R}}', \omega) \right]_{z=0} \\
& \quad \underbrace{\quad}_{=1} \\
& = \left[ K_{ez}^{\text{TM}}(\underline{\mathbf{R}}', \omega) \nabla \cdot \underbrace{\nabla G(\underline{\mathbf{R}} - \underline{\mathbf{R}}', \omega)}_{-k_0^2 G(\underline{\mathbf{R}} - \underline{\mathbf{R}}', \omega)} \right]_{z=0} \\
& = -K_{ez}^{\text{TM}}(\underline{\mathbf{R}}', \omega) k_0^2 G(\underline{\mathbf{R}} - \underline{\mathbf{R}}', \omega) \Big|_{z=0}
\end{aligned}$$

$$\begin{aligned}
& \nabla \times \nabla \times \left[ \underline{K}_{ez}(\underline{\mathbf{R}}', \omega) G(\underline{\mathbf{R}} - \underline{\mathbf{R}}', \omega) \right]_{z=0} = \underbrace{\underline{K}_{ez}(\underline{\mathbf{R}}', \omega) \cdot \nabla \nabla G(\underline{\mathbf{R}} - \underline{\mathbf{R}}', \omega)}_{=\underline{0}} - \underbrace{\underline{K}_{ez}(\underline{\mathbf{R}}', \omega) \nabla \cdot \nabla G(\underline{\mathbf{R}} - \underline{\mathbf{R}}', \omega)}_{=-K_{ez}^{\text{TM}}(\underline{\mathbf{R}}', \omega) k_0^2 G(\underline{\mathbf{R}} - \underline{\mathbf{R}}', \omega)} \Big|_{z=0} \\
& = K_{ez}^{\text{TM}}(\underline{\mathbf{R}}', \omega) k_0^2 G(\underline{\mathbf{R}} - \underline{\mathbf{R}}', \omega) \Big|_{z=0}
\end{aligned}$$

## 2-D Versions of EFIE: TM Case / 2D-Versionen von EFIE: TM-Fall

$$\begin{aligned}
& \underline{\epsilon}_z \cdot \nabla \times \nabla \times \oint_{\underline{\mathbf{R}}' \in S_{sc} = \partial V_{sc}} \underline{K}_{ez}(\underline{\mathbf{R}}', \omega) G(\underline{\mathbf{R}} - \underline{\mathbf{R}}', \omega) d^2 \underline{\mathbf{R}}' = \underline{\epsilon}_z \cdot \oint_{\underline{\mathbf{R}}' \in S_{sc} = \partial V_{sc}} \nabla \times \nabla \times \left[ \underline{K}_{ez}(\underline{\mathbf{R}}', \omega) G(\underline{\mathbf{R}} - \underline{\mathbf{R}}', \omega) \right] d^2 \underline{\mathbf{R}}' \\
& = -j \omega \epsilon_0 \underline{\epsilon}_z \cdot \underline{\mathbf{E}}^{sc}(\underline{\mathbf{R}}, \omega)
\end{aligned}$$

$$\begin{aligned}
& \nabla \times \nabla \times \left[ \underline{K}_{ez}(\underline{\mathbf{R}}', \omega) G(\underline{\mathbf{R}} - \underline{\mathbf{R}}', \omega) \right]_{z=0} = \underbrace{\underline{K}_{ez}(\underline{\mathbf{R}}', \omega) \cdot \nabla \nabla G(\underline{\mathbf{R}} - \underline{\mathbf{R}}', \omega)}_{=\underline{0}} - \underbrace{\underline{K}_{ez}(\underline{\mathbf{R}}', \omega) \nabla \cdot \nabla G(\underline{\mathbf{R}} - \underline{\mathbf{R}}', \omega)}_{=-K_{ez}^{\text{TM}}(\underline{\mathbf{R}}', \omega) k_0^2 G(\underline{\mathbf{R}} - \underline{\mathbf{R}}', \omega)} \Big|_{z=0} \\
& = K_{ez}^{\text{TM}}(\underline{\mathbf{R}}', \omega) k_0^2 G(\underline{\mathbf{R}} - \underline{\mathbf{R}}', \omega) \Big|_{z=0}
\end{aligned}$$

$$\begin{aligned}
& \underline{\epsilon}_z \cdot \oint_{\underline{\mathbf{R}}' \in S_{sc} = \partial V_{sc}} \nabla \times \nabla \times \left[ \underline{K}_{ez}(\underline{\mathbf{R}}', \omega) G(\underline{\mathbf{R}} - \underline{\mathbf{R}}', \omega) \right] d^2 \underline{\mathbf{R}}' \Big|_{z=0} = \oint_{\underline{\mathbf{R}}' \in S_{sc} = \partial V_{sc}} K_{ez}^{\text{TM}}(\underline{\mathbf{R}}', \omega) k_0^2 G(\underline{\mathbf{R}} - \underline{\mathbf{R}}', \omega) d^2 \underline{\mathbf{R}}' \Big|_{z=0} \\
& = -j \omega \epsilon_0 \underline{\epsilon}_z \cdot \underline{\mathbf{E}}^{sc}(\underline{\mathbf{R}}, \omega) \Big|_{z=0}
\end{aligned}$$

$$\begin{aligned}
& \underline{\epsilon}_z \cdot \underline{\mathbf{E}}^{sc}(\underline{\mathbf{R}}, \omega) \Big|_{z=0} = -\frac{k_0^2}{j \omega \epsilon_0} \oint_{\underline{\mathbf{R}}' \in S_{sc} = \partial V_{sc}} K_{ez}^{\text{TM}}(\underline{\mathbf{R}}', \omega) G(\underline{\mathbf{R}} - \underline{\mathbf{R}}', \omega) d^2 \underline{\mathbf{R}}' \Big|_{z=0} \\
& = j \omega \mu_0 \oint_{\underline{\mathbf{R}}' \in S_{sc} = \partial V_{sc}} K_{ez}^{\text{TM}}(\underline{\mathbf{R}}', \omega) G(\underline{\mathbf{R}} - \underline{\mathbf{R}}', \omega) d^2 \underline{\mathbf{R}}' \Big|_{z=0}
\end{aligned}$$

$$\underline{\mathbf{E}}_z^{sc}(\underline{\mathbf{R}}, \omega) \Big|_{z=0} = j \omega \mu_0 \oint_{\underline{\mathbf{R}}' \in S_{sc} = \partial V_{sc}} K_{ez}^{\text{TM}}(\underline{\mathbf{R}}', \omega) G(\underline{\mathbf{R}} - \underline{\mathbf{R}}', \omega) d^2 \underline{\mathbf{R}}' \Big|_{z=0}$$

## 2-D Versions of EFIE: TM Case / 2D-Versionen von EFIE: TM-Fall

$$\begin{aligned} E_z^{\text{sc}}(\underline{\mathbf{R}}, \omega) \Big|_{z=0} &= j\omega\mu_0 \left[ \oint \oint_{\underline{\mathbf{R}}' \in S_{\text{sc}} = \partial V_{\text{sc}}} K_{ez}^{\text{TM}}(\underline{\mathbf{R}}', \omega) G(\underline{\mathbf{R}} - \underline{\mathbf{R}}', \omega) d^2 \underline{\mathbf{R}}' \right] \Big|_{z=0} \\ &= j\omega\mu_0 \oint_{\underline{\mathbf{r}}' \in C_{\text{sc}} = \partial S_{\text{sc}}} K_{ez}^{\text{TM}}(\underline{\mathbf{r}}', \omega) \left[ \int_{z'=-\infty}^{\infty} G(\underline{\mathbf{R}} - \underline{\mathbf{R}}', \omega) dz' \right] \Big|_{z=0} d\underline{\mathbf{r}}' \end{aligned}$$

$$\begin{aligned} \left[ \int_{z'=-\infty}^{\infty} G(\underline{\mathbf{R}} - \underline{\mathbf{R}}', \omega) dz' \right] \Big|_{z=0} &= \left[ \int_{z'=-\infty}^{\infty} \frac{e^{jk_0 |\underline{\mathbf{R}} - \underline{\mathbf{R}}'|}}{4\pi |\underline{\mathbf{R}} - \underline{\mathbf{R}}'|} dz' \right] \Big|_{z=0} \\ &= \int_{z'=-\infty}^{\infty} \frac{e^{jk_0 |\underline{\mathbf{r}} - \underline{\mathbf{R}}'|}}{4\pi |\underline{\mathbf{r}} - \underline{\mathbf{R}}'|} dz' \\ &= \frac{j}{4} H_0^{(1)}(k_0 |\underline{\mathbf{r}} - \underline{\mathbf{R}}'|) \quad \text{Hankel function of 1st kind and 0th order /} \\ &\quad \text{Hankel-Funktion der 1. Art und 0. Ordnung} \end{aligned}$$

Scalar 2-D Green's function of free-space /  
Skalare 2-D Greensche Funktion des Freiraumes

$$G(\underline{\mathbf{r}} - \underline{\mathbf{r}}', \omega) = \frac{j}{4} H_0^{(1)}(k_0 |\underline{\mathbf{r}} - \underline{\mathbf{r}}'|)$$

## 2-D Versions of EFIE: TM Case / 2D-Versionen von EFIE: TM-Fall

$$E_z^{\text{sc}}(\underline{\mathbf{r}}, \omega) = j\omega\mu_0 \oint_{\underline{\mathbf{r}}' \in C_{\text{sc}} = \partial S_{\text{sc}}} K_{ez}^{\text{TM}}(\underline{\mathbf{r}}', \omega) G(\underline{\mathbf{r}} - \underline{\mathbf{r}}', \omega) d\underline{\mathbf{r}}', \quad \underline{\mathbf{r}} \in C_{\text{sc}}$$

Scalar 2-D Green's function of free-space /  
Skalare 2-D Greensche Funktion des Freiraumes

$$G(\underline{\mathbf{r}} - \underline{\mathbf{r}}', \omega) = \frac{j}{4} H_0^{(1)}(k_0 |\underline{\mathbf{r}} - \underline{\mathbf{r}}'|)$$

Integral representation of the scattered field at the scatterer /  
Integraldarstellung des Streufeldes auf dem Streuer

$$E_z^{\text{sc}}(\underline{\mathbf{r}}, \omega) = j\omega\mu_0 \oint_{\underline{\mathbf{r}}' \in C_{\text{sc}} = \partial S_{\text{sc}}} K_{ez}^{\text{TM}}(\underline{\mathbf{r}}', \omega) G(\underline{\mathbf{r}} - \underline{\mathbf{r}}', \omega) d\underline{\mathbf{r}}', \quad \underline{\mathbf{r}} \in C_{\text{sc}}$$

2-D PEC TM EFIE for the z component of the electric field strength /  
2D-IEL-TM-EFIE für die z-Komponente der elektrischen Feldstärke

$$E_z^{\text{sc}}(\underline{\mathbf{r}}, \omega) = -E_z^{\text{in}}(\underline{\mathbf{r}}, \omega), \quad \underline{\mathbf{r}} \in C_{\text{sc}}$$

Finally we obtain for the 2-D PEC TM EFIE / Schließlich erhalten wir für die 2D-IEL-TM-EFIE

$$j\omega\mu_0 \oint_{\underline{\mathbf{r}}' \in C_{\text{sc}} = \partial S_{\text{sc}}} K_{ez}^{\text{TM}}(\underline{\mathbf{r}}', \omega) G(\underline{\mathbf{r}} - \underline{\mathbf{r}}', \omega) d\underline{\mathbf{r}}' = -E_z^{\text{in}}(\underline{\mathbf{r}}, \omega), \quad \underline{\mathbf{r}} \in C_{\text{sc}}$$

This is a *Fredholm integral equation of the 1. kind* in form of a *closed line integral*  
for the unknown electric surface current density for a known incident field. /  
Dies ist eine *Fredholmsche Integralgleichung 1. Art* in Form eines *geschlossenen Linienintegrals*  
für die unbekannte elektrische Flächenladungsdichte für ein *bekanntes* einfallendes Feld.

## Method of Moments (MoM) – Introduction / Momenten-Methode (MoM) – Einleitung

$$2\text{-D-PEC-TM-EFIE} / \quad j\omega\mu_0 \oint_{\underline{r}' \in C_{sc}} =_{\partial S_{sc}} K_{ez}^{\text{TM}}(\underline{r}', \omega) G(\underline{r} - \underline{r}', \omega) d\underline{r}' = -E_z^{\text{in}}(\underline{r}, \omega), \quad \underline{r} \in C_{sc}$$



Linear Operator Equation /  
Lineare Operatorgleichung



Method of Moments (MoM) /  
Momentenmethode

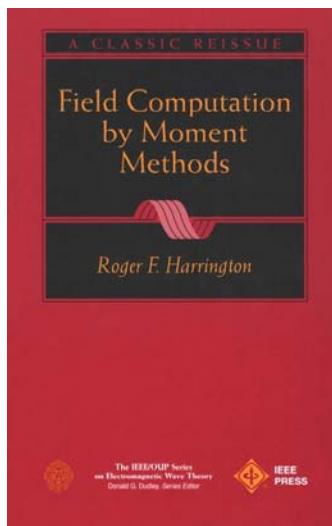
Linear Operator Equation /  
Lineare Operatorgleichung

$$[\mathbf{L}]\{\mathbf{f}\} = \{\mathbf{g}\}$$

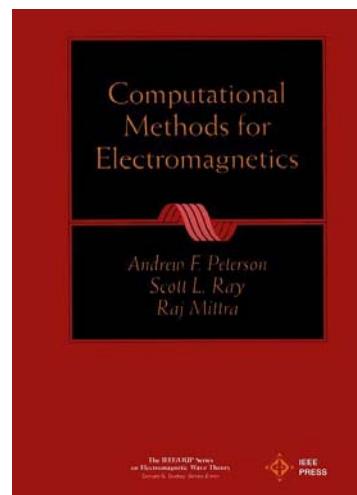
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## Method of Moments (MoM) – Introduction / Momenten-Methode (MoM) – Einleitung



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## Method of Moments (MoM) – Linear Operator Equation / Momenten-Methode (MoM) – Lineare Operatorgleichung

Linear Operator Equation /  
Lineare Operatorgleichung

$$\mathcal{L}\{f\} = g$$

[A]{x} = {b} (Linear) Matrix Equation /  
(Lineare) Matrixgleichung

with the Properties / mit den Eigenschaften

- $\mathbb{D}/\mathcal{L}$  is the **Domain** of  $\mathcal{L}$  /  
 $\mathbb{D}/\mathcal{L}$  ist der **Definitionsbereich** von  $\mathcal{L}$ .
- $\mathbb{R}/\mathcal{L}$  is the **Range** or Co-domain of  $\mathcal{L}$  /  
 $\mathbb{R}/\mathcal{L}$  ist der **Wertebereich** von  $\mathcal{L}$ .
- $\mathbb{D}$  and  $\mathbb{R}$  are **Function Spaces** and  $f \in \mathbb{D}, g \in \mathbb{R}$ . /  
 $\mathbb{D}$  und  $\mathbb{R}$  sind **Funktionsräume** und  $f \in \mathbb{D}, g \in \mathbb{R}$ .
- The Functional or **Inner Product** is defined by /  
Das Funktional oder **inneres Produkt** ist definiert durch

$$\langle f_1, f_2 \rangle := \int_{\mathbb{D}} f_1 f_2^* d\mathbb{D}$$

${}^{**}$ : Conjugate Complex /  
 ${}^{**}$ : konjugiert komplex

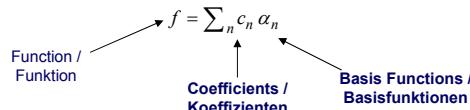
## Method of Moments (MoM) – Basis Function Expansion / Momenten-Methode (MoM) – Basisfunktionsentwicklung

Linear Operator Equation /  
Lineare Operatorgleichung

$$\mathcal{L}\{f\} = g$$

### Basis Function Expansion / Basisfunktionsentwicklung

Let  $\alpha_n$  a Basis in  $\mathbb{D}$ , i.e. the  $\alpha_n$  spans the domain  $\mathbb{D}$ , then we can represent  $f$  in form of series /  
Sei  $\alpha_n$  eine Basis von  $\mathbb{D}$ , d.h. die  $\alpha_n$  spannen den Raum  $\mathbb{D}$  auf, dann lässt sich  $f$  in Form einer Reihe darstellen



Because of the Linearity of the Operator  $\mathcal{L}$  / Wegen der Linearität des Operator  $\mathcal{L}$

$$\begin{aligned} \mathcal{L}\{f\} &= \mathcal{L}\left\{\sum_n c_n \alpha_n\right\} \\ &= \sum_n c_n \mathcal{L}\{\alpha_n\} \\ &= g \end{aligned}$$

## Method of Moments (MoM) – Formulation (2) / Momenten-Methode (MoM) – Formulierung (2)

Linear Operator Equation /  
Lineare Operatorgleichung

$$\mathcal{L}\{f\} = g$$

### Testing Procedure: Weighting Functions / Testprozedur: Gewichtungsfunktionen

Let  $w_m$  a the weighting functions – Testing Functions – of  $\mathbb{R}$ , then the following projection theorem holds /  
Seien  $w_m$  die Gewichtungsfunktionen – Testfunktionen – in  $\mathbb{R}$ , dann gilt der Projektionsatz

$$\langle w_m, \mathcal{L}\{f\} \rangle = \langle w_m, g \rangle$$

$$\langle w_m, \mathcal{L}\{f\} - g \rangle = 0 \quad \forall m$$

$$\langle w_m, \mathcal{L}\{\sum_n c_n \alpha_n\} \rangle = \langle w_m, g \rangle$$

$$\sum_n c_n \langle w_m, \mathcal{L}\{\alpha_n\} \rangle = \langle w_m, g \rangle$$

### System of Linear Equations / Linear Gleichungssystem

$$[\mathbf{L}]\{\mathbf{f}\} = \{\mathbf{g}\} \leftrightarrow \sum_n L_{mn} f_n = g_m$$

## Method of Moments (MoM) – Selection of Basis and Weighting (Testing) Functions / Momenten-Methode (MoM) – Wahl der Basis- und Gewichtungs(Test)funktionen

Basis Functions are  $\alpha_n$  and Weighting Functions (Testing Functions) are  $w_m$  /  
Basisfunktionen sind die  $\alpha_n$  und Gewichtungsfunktionen (Testfunktionen) sind die  $w_m$

1. Let  $w_m = \alpha_n$  a, then we call this the Method of Galerkin /  
Sind die  $w_m = \alpha_n$ , dann sprechen wir von der Galerkin-Methode
2. Let  $w_m = \mathcal{L}\{\alpha_m\}$ , which results in the Least Square Method. The Method of Moments gives then an approximation with the least quadratic mean value. /  
Sind die  $w_m = \mathcal{L}\{\alpha_m\}$ , dann erhält man die Methode der kleinsten Fehlerquadrate. Die Momenten-Methode liefert dann eine Approximation mit dem kleinsten quadratischen Mittelwert.

$$L_{mn} = \langle \mathcal{L}\{\alpha_m\}, \mathcal{L}\{\alpha_n\} \rangle$$

Now we define a error functional / Nun definieren wir ein Fehlerfunktional

$$r^N := \sum_{n=1}^N c_n \alpha_n - g$$

and build the mean quadratic error / und bilden den mittleren quadratischen Fehler

$$\langle r^N, r^N \rangle$$

then we minimize the error if / so wird der Fehler minimal für

$$w_m = \mathcal{L}\{\alpha_m\}$$

## Method of Moments (MoM) – Selection of Basis and Weighting (Testing) Functions / Momenten-Methode (MoM) – Wahl der Basis- und Gewichtungs(Test)funktionen

Basis Functions are  $\alpha_n$  and Weighting Functions (Testing Functions) are  $w_m$  /  
Basisfunktionen sind die  $\alpha_n$  und Gewichtungsfunktionen (Testfunktionen) sind die  $w_m$

### 1. Entire Domain Basis Functions / Ganzbereichsbasisfunktionen

The basis functions  $\alpha_n$  are defined over the complete domain  $\mathbb{D}$ .

Examples are:

$$\sin(x), \cos(x), e^{jx}$$

Die Basisfunktionen  $\alpha_n$  sind über den gesamten Definitionsbereich  $\mathbb{D}$  definiert.

Beispiele sind:

$$\sin(x), \cos(x), e^{jx}$$

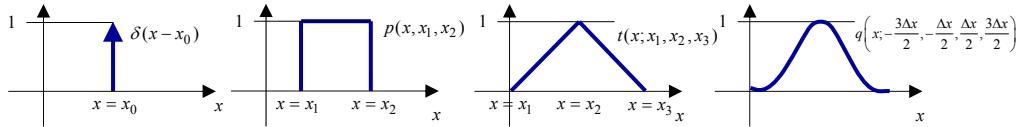
### 2. Subdomain Basis Functions / Unterbereichsbasisfunktionen

The basis functions  $\alpha_n$  are defined over subdomain of the domain  $\mathbb{D}$ .

Examples are: Delta Function, Rectangular Pulse (or Piecewise-Constant) Function, Triangular Pulse Function, Quadratic Spline Function

Die Basisfunktionen  $\alpha_n$  sind über einen Unterbereich des Bereichs  $\mathbb{D}$  definiert.

Beispiele sind: Delta-Funktion, Rechteckimpuls-Funktion, Dreieckimpuls-Funktion, Quadratische Spline Funktion

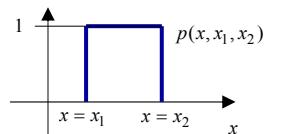


## Method of Moments (MoM) – Selection of Basis and Weighting (Testing) Functions / Momenten-Methode (MoM) – Wahl der Basis- und Gewichtungs(Test)funktionen

### Delta Function / Delta-Funktion



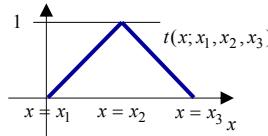
### Rectangular Pulse (or Piecewise-Constant) Function / Rechteckimpuls-Funktion (oder stückweise konstante Funktion)



$$B_1(x) = p(x; x_1, x_2) = \begin{cases} 1 & x_1 \leq x \leq x_2 \\ 0 & \text{otherwise / sonst} \end{cases}$$

## Method of Moments (MoM) – Selection of Basis and Weighting (Testing) Functions / Momenten-Methode (MoM) – Wahl der Basis- und Gewichtungs(Test)funktionen

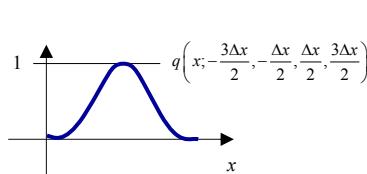
### Triangular Pulse Function / Dreieckimpulsfunktion



$$B_2(x) = t(x; x_1, x_2, x_3) = \begin{cases} \frac{x - x_1}{x_2 - x_1} & x_1 \leq x \leq x_2 \\ \frac{x_3 - x}{x_3 - x_2} & x_2 < x \leq x_3 \\ 0 & \text{sonst} \end{cases}$$

otherwise / sonst

### Quadratic Spline Function / Quadratische Spline-Funktion



$$B_2(x) = q\left(x; -\frac{3\Delta x}{2}, -\frac{\Delta x}{2}, \frac{\Delta x}{2}, \frac{3\Delta x}{2}\right) = \begin{cases} 0 & x < -\frac{3\Delta x}{2} \\ \frac{9}{8} + \frac{3x}{2\Delta x} + \frac{x^2}{2(\Delta x)^2} & -\frac{3\Delta x}{2} \leq x < -\frac{\Delta x}{2} \\ \frac{3}{4} - \frac{x^2}{(\Delta x)^2} & -\frac{\Delta x}{2} \leq x < \frac{\Delta x}{2} \\ \frac{9}{8} - \frac{3x}{2\Delta x} + \frac{x^2}{2(\Delta x)^2} & \frac{\Delta x}{2} \leq x < \frac{3\Delta x}{2} \\ 0 & x > \frac{3\Delta x}{2} \end{cases}$$

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## Method of Moments (MoM) – Example: Solution of a 1-D Boundary Value Problem / Momenten-Methode (MoM) – Beispiel: Lösung eines 1D-Randwertproblems

Given is the boundary value problem / Gegeben ist der Randwertproblem

$$-\frac{d^2}{dx^2} f(x) = 1 + 4x^2 \quad \begin{aligned} f(x) &\text{ continuous for } x = [0, 1] \\ \text{Boundary conditions: } f(0) &= f(1) = 0 / \\ f(x) &\text{ stetig für } x = [0, 1] \\ \text{Randbedingungen: } f(0) &= f(1) = 0 \end{aligned}$$

Determine / Bestimme  $f(x) = ?$

$$\text{Basis Function Expansion / Basisfunktionsentwicklung} \quad f(x) = \sum_{n=1}^N c_n \alpha_n(x)$$

$$\text{Basis Functions / Basisfunktionen} \quad \alpha_n(x) = x - x^{n+1}$$

$$\text{Ensures the Boundary conditions / Erfüllt die Randbedingungen} \quad \alpha_n(0) = \alpha_n(1) = 0$$

$$\text{Inner Product / Inneres Produkt} \quad \langle f(x), g(x) \rangle := \int_0^1 f(x) g(x) dx$$

$$\langle f_1, f_2 \rangle := \int_{\mathbb{D}} f_1 f_2^* d\mathbb{D} \quad \mathbb{D} \rightarrow x = [0, 1]$$

## Method of Moments (MoM) – Example: Solution of a 1-D Boundary Value Problem / Momenten-Methode (MoM) – Beispiel: Lösung eines 1D-Randwertproblems

$$w_m(x) = \mathcal{L}\{\alpha_m(x)\}$$

$$\mathcal{L} = -\frac{d^2}{dx^2}$$

Testing Functions /  
Testfunktionen

$$\begin{aligned} w_m(x) &= \mathcal{L}\{x - x^{m+1}\} \\ &= -\frac{d^2}{dx^2}(x - x^{m+1}) \\ &= m(m+1)x^{m-1} \end{aligned}$$

$$\mathcal{L}\{f\} = g$$

$$\langle w_m(x), \mathcal{L}\{f(x)\} \rangle = \langle w_m(x), g(x) \rangle$$

$$g(x) = 1 + 4x^2$$

## Method of Moments (MoM) – Example: Solution of a 1-D Boundary Value Problem / Momenten-Methode (MoM) – Beispiel: Lösung eines 1D-Randwertproblems

$$\begin{aligned} \langle w_m(x), \mathcal{L}\{f(x)\} \rangle &= \langle w_m(x), g(x) \rangle \\ \langle w_m(x), \mathcal{L}\{f(x)\} \rangle &= \left\langle m(m+1)x^{m-1}, -\frac{d}{dx^2} \sum_{n=1}^N c_n (x - x^{n-1}) \right\rangle \\ &= \sum_{n=1}^N c_n \left\langle m(m+1)x^{m-1}, n(n+1)x^{n-1} \right\rangle \\ &= m(m+1) \sum_{n=1}^N n(n+1) c_n \int_{x=0}^1 x^{m-1} x^{n-1} dx \\ &= m(m+1) \sum_{n=1}^N \frac{n(n+1)}{m+n-1} c_n \\ \langle w_m(x), g(x) \rangle &= \left\langle m(m+1)x^{m-1}, (1+4x^2) \right\rangle \\ &= \int_{x=0}^1 m(m+1)x^{m-1} (1+4x^2) dx \\ &= m(m+1) \int_{x=0}^1 (x^{m-1} + 4x^{m+1}) dx \\ &= \frac{(5m+1)(m+1)}{m+2} \end{aligned}$$

$$\begin{aligned} L_{mn} &= m(m+1) \frac{n(n+1)}{m+n-1} \\ [\mathbf{L}]\{\mathbf{f}\} &= \{\mathbf{g}\} \quad \sum_n L_{mn} f_n = g_m \\ f_n &= c_n \\ g_m &= \frac{(5m+1)(m+1)}{m+2} \end{aligned}$$

**Method of Moments (MoM) – Example: Solution of a 1-D Boundary Value Problem /  
Momenten-Methode (MoM) – Beispiel: Lösung eines 1D-Randwertproblems**

$$N = 1 \quad L_{11} = 4 \quad f_1(x) = \sum_{n=1}^1 c_n \alpha_n(x)$$

$$g_1 = \frac{14}{3} \quad = \sum_{n=1}^1 c_n (x - x^{n+1})$$

$$f_1 = c_1 = \frac{7}{6} \quad = \frac{7}{6} (x - x^2)$$

$$\mathcal{L}\{f_1(x)\} = \frac{7}{3} \neq 1 + 4x^2$$

$$N = 2 \quad [\mathbf{L}] = \begin{bmatrix} 4 & 6 \\ 6 & 12 \end{bmatrix} \quad f_2(x) = \sum_{n=1}^2 c_n \alpha_n(x)$$

$$\{\mathbf{g}\} = \begin{Bmatrix} \frac{14}{3} \\ 9 \end{Bmatrix} \quad = \sum_{n=1}^2 c_n (x - x^{n+1})$$

$$\{\mathbf{f}\}_2 = \{\mathbf{c}\}_2 = \begin{Bmatrix} 1 \\ \frac{6}{6} \\ \frac{2}{3} \end{Bmatrix} \quad = \frac{1}{6}(x - x^2) + \frac{2}{3}(x - x^3)$$

$$= \frac{5}{6}x - \frac{1}{6}x^2 - \frac{2}{3}x^3$$

$$\mathcal{L}\{f_2(x)\} = \frac{1}{3} + 4x \neq 1 + 4x^2$$

**Method of Moments (MoM) – Example: Solution of a 1-D Boundary Value Problem /  
Momenten-Methode (MoM) – Beispiel: Lösung eines 1D-Randwertproblems**

$$N = 3 \quad [\mathbf{L}] = \begin{bmatrix} 4 & 6 & 8 \\ 6 & 12 & 18 \\ 8 & 18 & \frac{144}{5} \end{bmatrix} \quad f_3(x) = \sum_{n=1}^3 c_n \alpha_n(x)$$

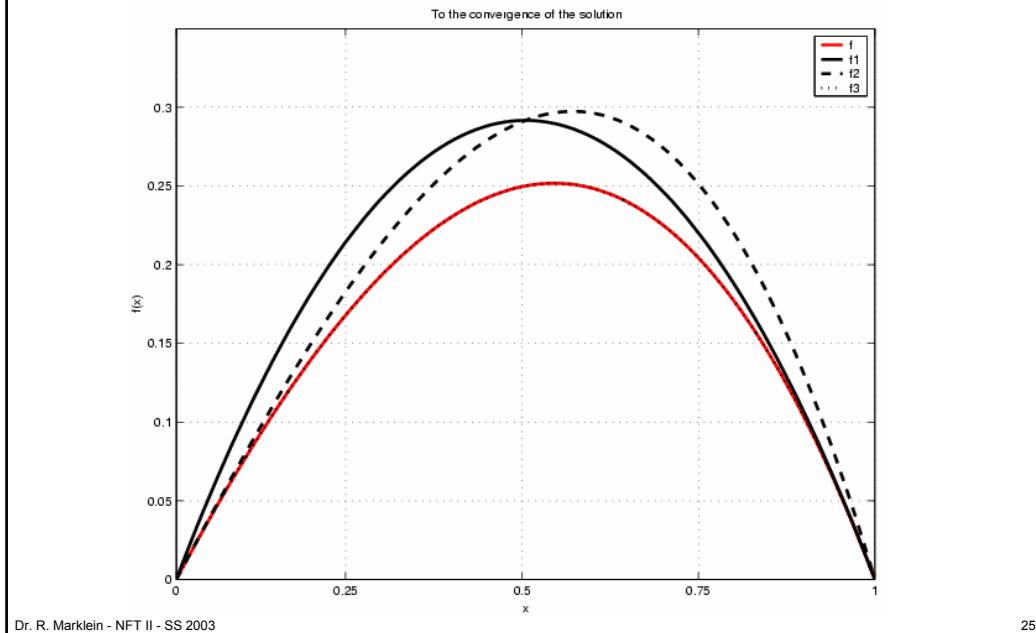
$$\{\mathbf{g}\} = \begin{Bmatrix} \frac{14}{3} \\ 9 \\ \frac{68}{5} \end{Bmatrix} \quad = \sum_{n=1}^3 c_n (x - x^{n+1})$$

$$\{\mathbf{f}\}_3 = \{\mathbf{c}\}_3 = \begin{Bmatrix} \frac{1}{2} \\ 0 \\ \frac{1}{3} \end{Bmatrix} \quad = \frac{1}{2}(x - x^2) + \frac{1}{3}(x - x^4)$$

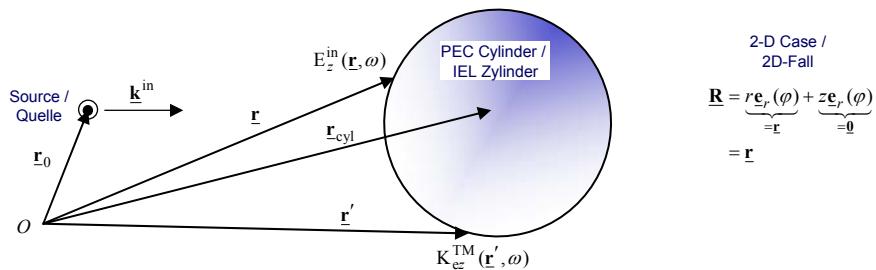
$$= \frac{5}{6}x - \frac{1}{2}x^2 - \frac{1}{3}x^4$$

$$\mathcal{L}\{f_3(x)\} = 1 + 4x^2$$

**Method of Moments (MoM) – Example: Solution of a 1-D Boundary Value Problem /  
Momenten-Methode (MoM) – Beispiel: Lösung eines 1D-Randwertproblems**



**EM Scattering by a Perfectly Electrically Conducting Cylinder: EFIE Discretized in the 2-D TM Case with Pulse Basis and Delta Testing Functions / EM-Streuung an einem ideal elektrisch leitendem Zylinder: EFIE diskretisiert im 2D-TM-Fall mit Impuls-Basisfunktionen und Delta-Testfunktionen**



2-D PEC TM EFIE / 2D-IEL-TM-EFIE

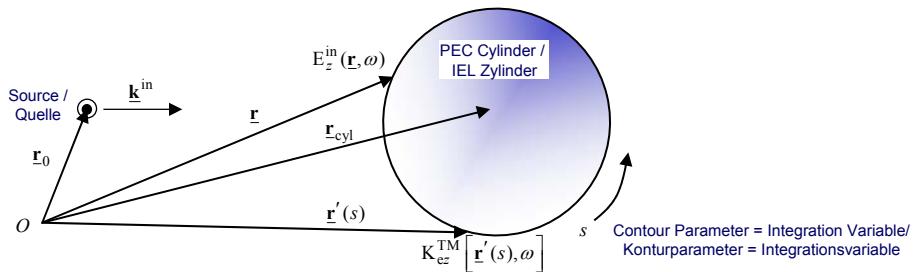
$$j\omega\mu_0 \oint_{\underline{r}' \in C_{sc} = \partial S_{sc}} K_{ez}^{TM}(\underline{r}', \omega) G(\underline{r} - \underline{r}', \omega) d\underline{r}' = -E_z^{in}(\underline{r}, \omega), \quad \underline{r} \in C_{sc}$$

This is a *Fredholm integral equation of the 1. kind* in form of a *closed line integral* for the unknown electric surface current density for a known incident field. /

Dies ist eine *Fredholmsche Integralgleichung 1. Art* in Form eines *geschlossenen Linienintegrals* für die unbekannte elektrische Flächenladungsdichte für ein bekanntes einfallendes Feld.

$$G(\underline{r} - \underline{r}', \omega) = \frac{j}{4} H_0^{(1)} \left( k_0 |\underline{r} - \underline{r}'| \right)$$

**EM Scattering by a Perfectly Electrically Conducting Cylinder: EFIE Discretized in the 2-D TM Case with Pulse Basis and Delta Testing Functions / EM-Streuung an einem ideal elektrisch leitendem Zylinder: EFIE diskretisiert im 2D-TM-Fall mit Impuls-Basisfunktionen und Delta-Testfunktionen**



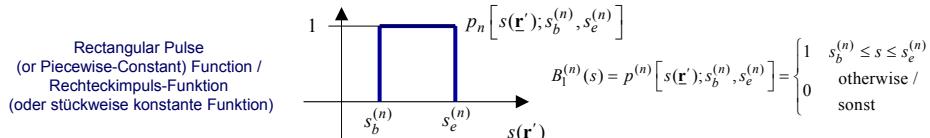
$$\begin{aligned}\underline{r}' &\rightarrow \underline{r}'(s) \\ K_{ez}^{TM}(\underline{r}', \omega) &\rightarrow K_{ez}^{TM}[\underline{r}'(s), \omega] \quad \underline{r}'(s) \in C_{sc} \quad C_{sc} : s_b \leq s \leq s_e \\ G(\underline{r} - \underline{r}', \omega) &\rightarrow G(\underline{r} - \underline{r}'(s), \omega)\end{aligned}$$

$$E_z^{in}(\underline{r}, \omega) = -j\omega\mu_0 \int_{s=s_b}^{s_e} G(\underline{r} - \underline{r}'(s), \omega) K_{ez}^{TM}[\underline{r}'(s), \omega] d\underline{r}'(s) \quad \underline{r} \in C_{sc}$$

**EM Scattering by a Perfectly Electrically Conducting Cylinder: EFIE Discretized in the 2-D TM Case with Rectangular Pulse Basis and Delta Testing Functions / EM-Streuung an einem ideal elektrisch leitendem Zylinder: EFIE diskretisiert im 2D-TM-Fall mit Rechteckimpuls-Basisfunktionen und Delta-Testfunktionen**

$$E_z^{in}(\underline{r}, \omega) = -j\omega\mu_0 \int_{s=s_b}^{s_e} G(\underline{r} - \underline{r}'(s), \omega) K_{ez}^{TM}[\underline{r}'(s), \omega] d\underline{r}'(s) \quad \underline{r} \in C_{sc}$$

**Basis Function Expansion using Rectangular Pulse Basis / Basisfunktionsentwicklung mit Rechteckimpulsfunktionen**



$$K_{ez}^{TM}[\underline{r}'(s), \omega] \approx \sum_{n=1}^N K_{ez}^{TM(n)}(\omega) p^{(n)}[s(\underline{r}'); s_b^{(n)}, s_e^{(n)}]$$

$$\begin{aligned}E_z^{in}(\underline{r}, \omega) &\approx -j\omega\mu_0 \sum_{n=1}^N K_{ez}^{TM(n)}(\omega) \int_{s=s_b^{(n)}}^{s_e^{(n)}} G(\underline{r} - \underline{r}'(s), \omega) p^{(n)}[s(\underline{r}'); s_b^{(n)}, s_e^{(n)}] d\underline{r}'(s) \quad \underline{r} \in C_{sc} \\ &\approx -j\omega\mu_0 \sum_{n=1}^N K_{ez}^{TM(n)}(\omega) \int_{s=s_b^{(n)}}^{s_e^{(n)}} G(\underline{r} - \underline{r}'(s), \omega) d\underline{r}'(s)\end{aligned}$$

**EM Scattering by a Perfectly Electrically Conducting Cylinder: EFIE Discretized in the 2-D TM Case with Pulse Basis and Delta Testing Functions / EM-Streuung an einem ideal elektrisch leitendem Zylinder: EFIE diskretisiert im 2D-TM-Fall mit Impuls-Basisfunktionen und Delta-Testfunktionen**

$$E_z^{\text{in}}(\underline{r}, \omega) \approx -j\omega\mu_0 \sum_{n=1}^N K_{ez}^{\text{TM}(n)}(\omega) \int_{s=s_b^{(n)}}^{s_e^{(n)}} G[\underline{r} - \underline{r}'(s), \omega] d\underline{r}'(s)$$

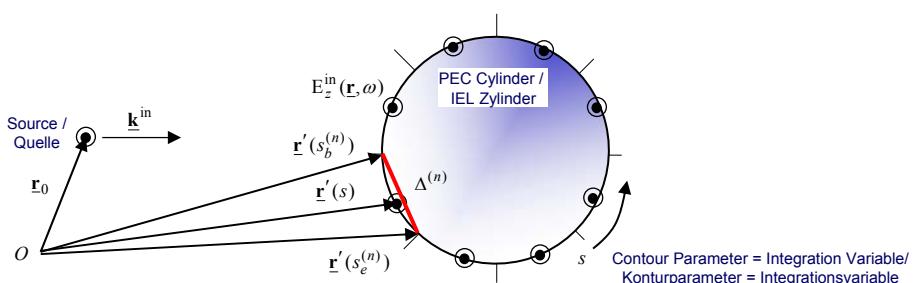
$$G[\underline{r} - \underline{r}'(s), \omega] = \frac{j}{4} H_0^{(1)}[k_0 |\underline{r} - \underline{r}'(s)|]$$

$$E_z^{\text{in}}(\underline{r}, \omega) \approx -j\omega\mu_0 \sum_{n=1}^N K_{ez}^{\text{TM}(n)}(\omega) \int_{s=s_b^{(n)}}^{s_e^{(n)}} \frac{j}{4} H_0^{(1)}[k_0 |\underline{r} - \underline{r}'(s)|] d\underline{r}'(s)$$

$$\approx \frac{\omega\mu_0}{4} \sum_{n=1}^N K_{ez}^{\text{TM}(n)}(\omega) \int_{s=s_b^{(n)}}^{s_e^{(n)}} H_0^{(1)}[k_0 |\underline{r} - \underline{r}'(s)|] d\underline{r}'(s)$$

$$\int_{s=s_b^{(n)}}^{s_e^{(n)}} H_0^{(1)}[k_0 |\underline{r} - \underline{r}'(s)|] d\underline{r}'(s) = ?$$

**EM Scattering by a Perfectly Electrically Conducting Cylinder: EFIE Discretized in the 2-D TM Case with Pulse Basis and Delta Testing Functions / EM-Streuung an einem ideal elektrisch leitendem Zylinder: EFIE diskretisiert im 2D-TM-Fall mit Impuls-Basisfunktionen und Delta-Testfunktionen**



$$\Delta^{(n)} = |\underline{r}'(s_b^{(n)}) - \underline{r}'(s_e^{(n)})|$$

$$\int_{s=s_b^{(n)}}^{s_e^{(n)}} d\underline{r}'(s) \approx |\underline{r}'(s_b^{(n)}) - \underline{r}'(s_e^{(n)})|$$

$$= \Delta^{(n)}$$

**EM Scattering by a Perfectly Electrically Conducting Cylinder: EFIE Discretized in the 2-D TM Case with Pulse Basis and Delta Testing Functions / EM-Streuung an einem ideal elektrisch leitendem Zylinder: EFIE diskretisiert im 2D-TM-Fall mit Impuls-Basisfunktionen und Delta-Testfunktionen**

**Power Series Approximation of the Main Diagonal Elements /  
Potenzreihenapproximation der Hauptdiagonalelemente**

$$H_0^{(1)}(z) = J_0(z) + jN_0(z)^2$$

**End of 3rd Lecture /  
Ende der 3. Vorlesung**